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Product manual AE200270 p. 1/11



Frederiksen Scientific's Universal Timer is designed for **timing** and **counting** using a wide range of equipment from Frederiksen Scientific and others:

Microphones, photogates, Geiger sensors, Free fall apparatus, Launch equipment for air track – and any electrical switch you can connect to the 4 mm safety sockets!

We created the Universal Timer with *science education* in mind. Measurements are precise and operation is simple.

Use standard lab leads with shrouded or unshrouded banana plugs for the 4 mm sockets.

Included: Modular cables for microphones, photogates etc., USB communication adapter, power adapter (12 V / 1.5 A).

Functions of the Universal Timer

Mechanical experiments:

- Start / Stop
- Collision
- Acceleration

Periodic events:

- Period
- Pendulum Period

Frequency measurements, Doppler effect:

- Frequency
- Sound Frequency
- Frequency, gated

Radioactivity etc.:

- Geiger
- Geiger, continuous
- Hi-Speed events

The Universal Timer speaks *six different languages* (configured in the *Options* menu).



Inputs and signals

The Universal Timer reacts on signals in two channels A and B. Each channel is associated with a modular connector, a set of 4 mm safety connectors, and a button.

Modular connector

The modular connector is used for connection to a range of Frederiksen Scientific products like photogates, microphones, or Geiger sensors.

The modular connector features a 5 V power output for the external equipment, an analogue input, a digital input and a digital "external reset" input.

Digital signal levels are 0 and 5 V.

The analogue input is AC coupled and is optimised for sharp, pulse-like signals. It has its maximum gain (x 100) around 5 kHz and is primarily aimed at microphone signals.

The modular connector inputs are only protected against minor overloads.

4 mm safety sockets

The 4 mm safety sockets establish the rugged connection to any equipment that can deliver a logic signal with 0 to 5 V levels.

The red sockets are the signal inputs to the two channels. The black sockets are ground / neutral / 0 V.

There is an internal pull-up resistor to 5 V, meaning that a simple switch can function as a signal source. (Like in our 198010 Free Fall Apparatus.)

These inputs tolerate sustained overloads up to $\pm 50 \text{ V}$ DC or 50 V AC.

Buttons

Each channel has one button associated. In some functions, a button press will act just like an input on the sockets.

The \blacktriangle button can also be called "button A". Similarly, the \triangledown button doubles as "button B".



Other connectors

On the back panel of the timer there is a DC input for a 12 V power adapter. Use this option to power the timer to save battery.

The last connector on the back panel is a 3.5 mm jack connector for an optional 512565 USB Communication Adapter. Through this connection, data is sent to a spreadsheet on a computer. This is great for instance if you need to show the results on a large display or projector. More on this in the *Data Streaming* paragraph below.

Functions Menu

FUNCTIONS:	ÊËÏ
Start/Stop	
> Collision	<
Acceleration	

The menu is displayed through a "window" that shows three lines at a time. You scroll up and down in the menu using the buttons \blacktriangle and \blacktriangledown .

Select the highlighted function by pressing \checkmark (Menu/Select).

The following sections describe each of the individual functions in detail.

Start / Stop



This function times the interval from a *Start event* (in either channel A or B) to a *Stop event* (in the opposite channel).

Events can be any of the following:

- A button presses or button release
- A low-to-high or a high-to-low signal on a digital input



• A sound signal that exceeds a given threshold on an analogue input.

If the *Show symbols* option is turned *Off* in the *Options* menu, the result will be presented with the description $A \hat{I} B$ (if channel A started the timer and Channel B stopped it) - or $B \hat{I} A$ (in the opposite case).

If the *Show symbols* option is turned *On* in the *Options* menu, symbols \dot{e} , \dot{e} , \dot{E} or \sim will be shown as the source of the *Start* and *Stop* events.

Example: BÈ Î Aè means that the *Start event* was a high-to-low transition on a digital input of channel B, and the *Stop event* was \blacktriangle (button A) being pressed.

Collision



The purpose of this function is to measure *passage times* of two photogates. From the passage time and the dimension of the object passing through the photogate, the speed can be calculated. Only the duration of each passage is measured - the times between passages are ignored.

A collision sequence consists of 4 such passages.

Any type of input may begin or end a passage timing - although digital inputs will probably be the only ones used in practice.

Example: In an elastic collision experiment, the sequence *could* be:

1) The passing of cart A through photogate A

2) The passing of cart B through photogate B (The two carts heading towards a collision between the two photogates) - followed by

3) The passing of cart B through photogate B

4) The passing of cart A through photogate A (The two carts returning away from the collision.)

To accommodate *any* possible collision between two objects, no assumption of the source or the order of events is made, if four passages is involved. Imagine a collision on an inclined plane where both carts are started upwards, collide, and return downwards again, passing the *same* photogate four times in total. This is still considered a valid sequence.

In case of for instance an inelastic collision, you may want to terminate the sequence manually. This is accomplished simply by pressing and releasing one of the buttons the necessary number of times. (Ignore these "artificial" passage times in the analysis.)

The four passage times will be listed in chronological order of the events that *initiated* the passage.

If the *Show symbols* option is turned *Off* in the *Options* menu, each passage time will be presented with the description Pass A or Pass B.

If the Show symbols option is turned On in the Options menu, details of each passage will be given, like $A \dot{E} \hat{I} A \dot{E}$, meaning that the passage started with channel A going high-to-low and ended with the input going low-to-high.

Any input, included buttons and sound, may trigger a passage timing; however, sound inputs will not give meaningful results in this context.

Acceleration

Acceleration	Accelera	tion
Ready	Pass A ΑÎΒ Pacc Δ	583.164 ms 2.11080 s 571.683 ms

The purpose of this function is to enable the calculation of an acceleration, based on the velocity of an object at two positions and the time it takes to go from one position to the other. The acceleration is typically assumed to be constant.

The velocities are calculated from measurements of *two passage times*. The *time interval* between the beginnings of the two passages is also measured. Typically, this involves two photogates.

As for the Start / Stop function, the channels are symmetrical: Both channels can measure *either* the first *or* the last passage time. As soon as a channel has been used, it will become inactive.

If the Show symbols option is turned Off in the Options menu, the passage times will be presented with the description Pass A resp. Pass B. The interval time will for example be designated A $\hat{1}$ B.



If the Show symbols option is turned On in the Options menu, details of each passage will be given, like AÈ î AÉ, meaning that the passage started with channel A going high-to-low and ended with the input going low-to-high. Similarly, the interval time will be given like AÈ î BÈ, describing that the interval timing started when A went high-to-low and ended when B went high-to-low.

Simple use of acceleration measurements

Let us call the two passage times t_A and t_B and let t_{AB} be the measured time interval. The length of the flag that breaks the light in the photogates is called Δx .

Call the velocities of the cart when passing the two photogates v_A and v_B .

Assuming that the acceleration is constant, we have this approximate formula:

$$a = \frac{\Delta v}{\Delta t} = \frac{v_{\rm B} - v_{\rm A}}{t_{\rm AB}} = \frac{\frac{\Delta x}{t_{\rm B}} - \frac{\Delta x}{t_{\rm A}}}{t_{\rm AB}}$$

If the relative difference between the velocities is not too extreme, this formula will give good results - in practice this is ensured by letting the cart gain some speed before entering the first photogate.

Precise use of acceleration measurements

Still assuming that the acceleration is constant, a thorough analysis of the measurement situation will reveal that the formula given above suffers from a systematic error. In case the cart is started close to the first photogate, this may be too large to ignore. The same analysis can lead to the following corrected version of the formula for the acceleration:

$$a = \frac{\frac{\Delta x}{t_{\rm B}} - \frac{\Delta x}{t_{\rm A}}}{t_{\rm AB} + \frac{1}{2}t_{\rm B} - \frac{1}{2}t_{\rm A}}$$

If the acceleration is constant, this *formula* is exact. Results based on actual measurements will of course still have experimental uncertainties.

(In case you wonder why the simple formula is wrong: A photogate passage time gives an *average* speed that must lie somewhere between the speed at the entry and the exit of the photogate. The correct <u>time interval to be used in calculating</u> <u>the acceleration</u> is the time between the two instants when the cart's instantaneous speed exactly equalled the two measured average speeds. The <u>time interval measured</u>, on the other hand, starts at the entry of the first photogate and ends at the entry of the second - these are clearly not the correct two instants.)

Period

Period	[B]	Period	[B]
Ready		<t>= N =</t>	1.2994872 s

This function measures the period of a signal applied to channel B.

When the function is selected - and when **X** (Reset) is pressed - the state of the inputs of channel B is noted; a change away from this state is considered a *trigger* event.

For every trigger event (except for the very first), the time from the previous trigger event to the latest one is displayed as the period T.

This only holds in principle – very short periods are in practice bundled and averaged over a more manageable time interval.

Also displayed is the average period <T> and the total number of periods N. N is simply given by

N = number of trigger events -1.

If N exceeds 10^7 , a sliding (decaying) average is applied. Pressing **X** resets the average and number figures.

Any input of channel B can be the source of trigger events – even button presses. It is recommended in practical measurements that only one input is used.

Average period

The average is calculated like this:

 $< T > = \frac{\text{time since last reset}}{N}$



- Until N exceeds 10⁷.

After that, the following formula applies after each trigger event:

$$< T > = \frac{\text{time for the last } 10^7 \text{ periods } + T_{\text{new}}}{10^7 + 1}$$

For very short periods, T_{new} is found as an average over m periods and the expression changes to:

$$< T > = {{\rm time \ for \ the \ last \ 10^7 \ periods \ + \ m \cdot T_{\rm new}} \over {10^7 \ + \ m}}$$

(It still boils down to "total time divided by number of periods".)

Pendulum Period



This function is intended for measuring the period T of a pendulum that swings through a photogate. In this situation, every other passage must be ignored. This means for instance that the first result is not displayed until the *third* passage of the photogate.

Apart from that, the behaviour is just like the previous function. The average pendulum period <T> is displayed along with the number of pendulum periods *N*.

Frequency



The purpose of this function is to measure the frequency of a signal applied to channel B.

The frequency is the reciprocal value of the period, and this function therefore behaves very similar to the Period function - it just displays the frequency f and the average frequency $\langle f \rangle$ instead - along with the number of periods N. As before, N = number of trigger events -1. This means that the displayed frequency value in principle is calculated for every trigger event. In case of a noise-free signal, this will give a frequency measurement as fast as theoretically possible.

Again, high frequencies are calculated as an average over a number of periods; minimum measurement time is 0.25 seconds.

Except for extremely low frequencies, you will normally wait for a sufficient number of periods to pass and then use the average value. If the frequency is known to have changed, press **X** (Reset) to start a new averaging sequence.

Average frequency

The average is calculated like this:

$$\langle f \rangle = \frac{N}{\text{time since last reset}}$$

- Until *N* exceeds 10⁷.

After that, the following formula applies after each update. Updates happen at the first trigger event after a 0.25 seconds' minimum period:

$$\langle f \rangle = \frac{t_{\rm r} \cdot f_{\rm new} + t_{\rm A} \cdot f_{\rm A}}{t_{\rm r} + t_{\rm A}}$$

Here, t_r is the time interval since last update during which the frequency f_{new} was registered. The previous average frequency f_A was measured over the time t_A - the time for the previous 10⁷ periods.

(This is simply the time-weighted average of the latest frequency measurement and the previous average.)

Sound Frequency



This function behaves identical to the previous one - except that the digital inputs are disabled, leaving only the analogue input of the modular connector of channel B active.

This enables the use of e.g., our 248600 Microphone for measuring the frequency of



sounds. If the digital output of the microphone was allowed to interfere, the frequency would not be correct for certain sound levels.

Frequency, gated





The purpose of this function is to measure a "snapshot" of the frequency of a signal applied to channel B - at a time determined by a *gate signal* on channel A.

The duration of the gate signal is also measured.

The gate signal can simply be pressing \blacktriangle (button A) but could also come from e.g., a photogate.

The frequency is averaged over a certain *gate time* that can be selected in a menu. The actual gate time is extended until the next trigger event in channel B, meaning that the frequency will always be calculated for a number of complete periods.

The gate time menu is reached by pressing $\mathbf{\nabla}$ (button B).

After each measurement, **X** (Reset) must be pressed before a new gate signal is accepted.

Geiger





This function counts trigger events happening on channel B during a selected time interval. The purpose is primarily to measure count rates from a Geiger sensor (our item No. 513575).

A measurement is started by pressing \blacktriangle (button A). It may be stopped prematurely by pressing \blacktriangle again, but the registered number of events will then not be related to a precise time interval. (The time is only showed in whole seconds.)

During the measurement, the accumulated number of events *N*, and the time *T* are displayed "live".

If the measurement time is selected as 10 s, time will be shown like "4 / 10 s" (after 4 seconds in this example).

After each completed measurement, the counter will be zeroed and restarted automatically when you press \blacktriangle to start a new measurement. Resetting can of course also be accomplished manually by pressing **X** (Reset).

Measurement time is selected in a menu that is reached by pressing $\mathbf{\nabla}$ (button B).

A special timing selection is *Manual*. Selecting *Manual* timing means that you must terminate the measurement manually by pressing \blacktriangle again. This is typically used for very long-time intervals where the 1 second uncertainty can be neglected.

When *Manual* is selected, time displayed will be like "183 / 0 s" (after 183 seconds).

Geiger, continuous



This function is like the previous one, except that when a measurement is completed, the following happens:

1) The result is moved to a new line and is designated *Prev*

2) A new measurement is started *without any delay*

Select measurement time as 10 s (or longer) to enable you to write down the (previous) result while the new one accumulates. You can of course also use data streaming (through the serial port) to have these data entered automatically into a spreadsheet. (This still requires 10 s periods or longer to work.)

The total time of all measurements will be a multiple of the selected measurement time. There are no tiny pauses that will accumulate to a significant timing error after a long series of measurements. Likewise, no events are "dropped" between measurements.



High Speed Events





The purpose of this function is to stream *a list of time intervals between trigger events in channel B* to the serial port.

This can e.g. be used with a Geiger sensor to investigate certain statistical properties of radioactive decay processes. (Google the term "exponential distribution" or find our lab manual for the experiment.)

The signal slope that triggers an event can be changed by pressing \checkmark (button B). The slope selected is shown in the upper right corner of the display as É (low to high), È (high to low), or & (both slopes).

In order to accommodate a rather high average frequency of events, the signalling speed of the serial port is changed while this function is active. The actual signalling speed used for this function is selected in the *Options* menu and is shown here as a reminder.

The maximum throughput rate is proportional to the communication speed (see *Specifications* for the maximum rates at 230400 bps).

To stop streaming, press X (Reset) or ✓ (Menu)

When returning to the main menu, the "standard" speed is re-established. Please note that this change introduces a small delay after pressing the \checkmark button. If you impatiently press the button twice, you will end up in the same function again.

In order to maximize performance, the display will only show a static message during the high speed streaming.

The data protocol is described in *High speed streaming* (below).

Options



This is a submenu.

Note: In order to leave the *Options* sub-menu, you must scroll to the top line *Save* & *return* and press ✓ (Menu/Select).

The other items in the *Options* sub-menu will step through a range of possible values each time you press \checkmark .

Language

The options are *EN* (English), *DE* (German), *FR* (French), *NO* (Norwegian), *NL* (Dutch) and *DA* (Danish). Changes take place immediately.

Symbols

The options are *Yes* and *No*. Selecting *Yes* turns on a more detailed level of event description in the display. See details in previous paragraphs for the different functions.

HiSpeed bps

The options are 57600, 74880, 115200 and 230400. The numbers designate the speed (<u>Bits</u> <u>Per</u> <u>Second</u>) that the communication port operates at. Read more in the description of the *High Speed Events* function (above).



Data Streaming

The 3.5 mm jack connector on the back panel can be used with the included 512565 USB Communication Adapter. Connected to a PC, the adapter constitutes a serial (COM) port.

The output format for all functions - except for *High Speed Events* – Is intended for use with the Data Streamer plugin for Microsoft's Excel 365.

Frederiksen Scientific has published a spreadsheet that emulates a dashboard for the Universal Counter which may e.g., be used to show the contents of the display on a large screen or projector.

For use with Geiger counter data, a special spreadsheet is available that facilitates logging of data as a function of time.

Find the spreadsheets on our web site.

Note: For the spreadsheet to function properly, macros must be enabled. Please also read the instructions on the "Help" sheet available in both spreadsheets.

Communication protocol details

The communication parameters are the standard used with Data Streamer – *normally there will be no need to change anything*: 9600 bits per second, 8 data bits, 1 stop bit, no parity, no flow control.

When using the spreadsheets prepared by Frederiksen Scientific, everything else is taken care of.

If you want to use the data *for other purposes*, the following information may be useful:

Each line of data represents a snapshot of the display. Each line sent consists of three fields per display line. All fields are separated by a field separator that by default is a comma.

After each display line, a code is sent which is used for translating certain special display characters like \hat{E} , \acute{e} , \acute{E} etc. These characters may appear in the first and third field in each display line and are transmitted over the serial link as more "normal" characters.

The spreadsheets mentioned above provide translation back to sensible display characters.

The *Geiger, continuous* function has a special datalogging mode, where data is sent only after each *finished count*. This mode is initiated by sending the character stream "b1" through the serial interface. Standard streaming is restored by the command "b4".

The default data field separator is a comma. It is possible to change the field separator character by sending one of the following commands:

Command	Separator
b5	Comma
b6	Semicolon
b7	Space
b8	Tabulator



High speed streaming

The function *High Speed Events* also uses the communication port. However, the DataStreamer plugin for Excel seems to be unable to handle data at these speeds. Instead, we recommend a serial communication program like *RealTerm*.

RealTerm is highly configurable, but only small changes need to be done to the default setup. The following instructions are suited for RealTerm version 2.0. 1) Go to the *Port* tab, select the COM *Port* used and set *Baud* to the communication speed used by Universal Counter. Preferably as high as possible (230400 bps). Check that the rest of the parameters comply with this: 8 data bits, 1 stop bit, no parity, no flow control. Click *Change* to activate the settings.



2) Go to the *Capture* tab and specify the *File* that you want to use for the data. We suggest that you keep the "txt" file extension to facilitate working with the file later. Click *Start: Overwrite* just before you start the event streaming by pressing \blacktriangle on the Universal Timer. Now you can minimize the

RealTerm window as nothing happens here until your measurements are over.

When finished, stop the function on the timer by pressing \checkmark , then click *Stop Capture* in RealTerm.



The first sensible line in the file describes which slope is selected. The last line will be a note that the Universal Timer changes back to the standard 9600 bps communication speed. The data format is one line per event. The number designates the time interval since the previous event, measured in clock cycles. One clock cycle is 50 ns.



If you selected *Both* slopes, each line starts with a "0" or a "1" meaning resp. *falling* or *rising* slope, followed by a field separator (comma by default), followed by the time in clock cycles.

A typical experiment to use the *High Speed Events* function is the investigation of the distribution of time intervals between Geiger counter clicks when measuring radioactivity.

You can find a spreadsheet that can be used in the analysis of such data on our web site. Instructions are placed in a tab of the spreadsheet file. There is also a complete lab manual available for this experiment

Note: This function is intended for high speeds. In case the interval between two events is larger than 2^{32} clock cycles (approx. 3.5 minutes), an overflow will happen which will not be flagged by a warning.

Experiments

Frederiksen Scientific has created a range of experiments using the 200270 Universal Timer:

131412-EN Speed of sound in air of 131422-EN Speed sound in steel 134512-EN Fall Free Measuring g 134712-EN Newtons-second law 134722-EN Collisions on air track 135710-EN Circular motion w/ Conical Pendulum 135730-EN Conical pendulum - Measuring *q* 138410-EN Alpha Beta and Gamma Radiation 138490-EN Radioactivity and statistics

Experiment descriptions can be found on our web site along with **lab manuals** to download.

Compatibility of modular port inputs

Microphones:	Our			248600
Photogates:	Our	197550,		197570
	PASCO	ME-9498	and	similar
Geiger sensors:	Our 513	570, 5135°	75	

These are the most important examples presently – expect the list to be extended.

Compatibility of safety sockets inputs

These inputs will react on a voltage crossing the trigger level (see *Specifications* below).

The input is internally pulled up by a resistor (to 5 V), so triggering will also happen if you make or break a connection between the red and black sockets.

The following equipment is specifically suited for the Universal Timer's safety socket inputs:

198010 Free Fall Apparatus

198510 Switch box (f. electric launcher)



Specifications

Pinout, modular inputs

1	Analog in	4	Digital in	
2	(Not connected)	5	+ 5 V supply out	2111
3	Ground, 0 V	6	External reset	

Voltages

Nomi	nal 4 mm safety sock 4 mm safety sock Modular sockets	ets – Mod ets – Mod pin 1. Freq	ular sockets p ular sockets p uency 5 kHz:	trigg in 4. Low [.] in 4. High	er -to-high: -to-Low:		30 ו	levels 2.7 V DC 1.8 V DC mV RMS
Overl	Overload Modular inputs: Not protected – connect only to 5 V logic levels 4 mm safety sockets:							otection +5 V DC) 50 V AC
Timir	Ig							
Funda	amental timing pre	ecision (int	ernal clock):				0.2 ppm (0.0	0002 %)
Start/	Stop – Collision –	Accelerati	ion					
Absol	ute time resolutio	n:						1 µs
Maxir	num time:						140)73748 s
Minin	num Start/Stop: Collision & Accele	eration:		pul	se			width 0.5 μs 5 μs
Minin	num time betweer	n A and B i	nputs:					0
Perio	d – Pendulum Peri	iod – Frequ	iency – Sound	Frequen	cy – Frequency, g	ated		
Gate t (The g	time, single measu gate time is extend	urement (N ded to an ii	lote: <i>Frequenc</i> nteger numbe	<i>cy, gated</i> r of signa	has selectable ga l cycles)	te time):		0.25 s
Displa	y resolution:						7	7½ digits
Max f	requency (4 mm s	afety sock	ets, 5 V logic le	evels):				> 1 MHz
Geige	r – Geiger, cont.							
Meas	urement periods:				1, 10	0, 60, 100, 30	00 s (+ manua	l timing)
Max r	nanual counting ti	me:					999	999999 s
Max r	number of counts:						4294	1967295
High :	Speed Events							
Max Strea	sustained Single slope:3.5 Both slopes: ming will become	input erroneous	frequency or stop comp	(@ letely wh	communicatior en these rates are	n speed e exceeded.	230400	bps) kHz 1.8 kHz